

SM212, Eigenvalue method in 2×2 case

PROBLEM: Solve

$$\begin{cases} x' = ax + by, & x(0) = x_0, \\ y' = cx + dy, & y(0) = y_0. \end{cases}$$

soln: Let

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

- Find the eigenvalues. These are the roots of the characteristic polynomial

$$p(\lambda) = \det \begin{pmatrix} a - \lambda & b \\ c & d - \lambda \end{pmatrix} = \lambda^2 - (a + d)\lambda + (ad - bc).$$

Call them λ_1, λ_2 (in any order you like).

You can use the quadratic formula, for example to get them:

$$\lambda_1 = \frac{a + d}{2} + \frac{\sqrt{(a + d)^2 - 4(ad - bc)}}{2}, \quad \lambda_2 = \frac{a + d}{2} - \frac{\sqrt{(a + d)^2 - 4(ad - bc)}}{2}.$$

- Find the eigenvectors. If $b \neq 0$ then you can use the formulas

$$\vec{v}_1 = \begin{pmatrix} b \\ \lambda_1 - a \end{pmatrix}, \quad \vec{v}_2 = \begin{pmatrix} b \\ \lambda_2 - a \end{pmatrix}.$$

In general, you can get them by solving the **eigenvector equation** $A\vec{v} = \lambda\vec{v}$.

- Plug these into the following formulas:

(a) $\lambda_1 \neq \lambda_2$, real:

$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = c_1 \vec{v}_1 \exp(\lambda_1 t) + c_2 \vec{v}_2 \exp(\lambda_2 t).$$

(b) $\lambda_1 = \lambda_2 = \lambda$, real:

$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = c_1 \vec{v}_1 \exp(\lambda t) + c_2 (\vec{v}_1 t + \vec{p}) \exp(\lambda t),$$

where \vec{p} is any non-zero vector satisfying $(A - \lambda I)\vec{p} = \vec{v}_1$.

- (c) $\lambda_1 = \alpha + i\beta$, complex: write $\vec{v}_1 = \vec{u}_1 + i\vec{u}_2$, where \vec{u}_1 and \vec{u}_2 are both *real vectors*.

$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = c_1[\exp(\alpha t) \cos(\beta t) \vec{u}_1 - \exp(\alpha t) \sin(\beta t) \vec{u}_2] \\ + c_2[-\exp(\alpha t) \cos(\beta t) \vec{u}_2 - \exp(\alpha t) \sin(\beta t) \vec{u}_1].$$

Examples

Example 1 *Solve*

$$x'(t) = x(t) - y(t), \quad y'(t) = 4x(t) + y(t), \quad x(0) = -1, \quad y(0) = 1.$$

Let

$$A = \begin{pmatrix} 1 & -1 \\ 4 & 1 \end{pmatrix}$$

and so the characteristic polynomial is

$$p(x) = \det(A - xI) = x^2 - 2x + 5.$$

The eigenvalues are

$$\lambda_1 = 1 + 2i, \quad \lambda_2 = 1 - 2i,$$

so $\alpha = 1$ and $\beta = 2$. Eigenvectors \vec{v}_1, \vec{v}_2 are given by

$$\vec{v}_1 = \begin{pmatrix} -1 \\ 2i \end{pmatrix}, \quad \vec{v}_2 = \begin{pmatrix} -1 \\ -2i \end{pmatrix},$$

though we actually only need to know \vec{v}_1 . The real and imaginary parts of \vec{v}_1 are

$$\vec{u}_1 = \begin{pmatrix} -1 \\ 0 \end{pmatrix}, \quad \vec{u}_2 = \begin{pmatrix} 0 \\ 2 \end{pmatrix}.$$

The solution is then

$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = \begin{pmatrix} -c_1 \exp(t) \cos(2t) + c_2 \exp(t) \sin(2t) \\ -2c_1 \exp(t) \sin(2t) - 2c_2 \exp(t) \cos(2t) \end{pmatrix},$$

so $x(t) = -c_1 \exp(t) \cos(2t) + c_2 \exp(t) \sin(2t)$ and $y(t) = -2c_1 \exp(t) \sin(2t) - 2c_2 \exp(t) \cos(2t)$.

Since $x(0) = -1$, we solve to get $c_1 = 1$. Since $y(0) = 1$, we get $c_2 = -1/2$. The solution is: $x(t) = -\exp(t) \cos(2t) - \frac{1}{2} \exp(t) \sin(2t)$ and $y(t) = -2 \exp(t) \sin(2t) + \exp(t) \cos(2t)$.

Example 2 *Solve*

$$x'(t) = -2x(t) + 3y(t), \quad y'(t) = -3x(t) + 4y(t).$$

Let

$$A = \begin{pmatrix} -2 & 3 \\ -3 & 4 \end{pmatrix}$$

and so the characteristic polynomial is

$$p(x) = \det(A - xI) = x^2 - 2x + 1.$$

The eigenvalues are

$$\lambda_1 = \lambda_2 = 1.$$

An eigenvector \vec{v}_1 is given by

$$\vec{v}_1 = \begin{pmatrix} 3 \\ 3 \end{pmatrix}.$$

Since we can multiply any eigenvector by a non-zero scalar and get another eigenvector, we shall use instead

$$\vec{v}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}.$$

Let $\vec{p} = \begin{pmatrix} r \\ s \end{pmatrix}$ be any non-zero vector satisfying $(A - \lambda I)\vec{p} = \vec{v}_1$. This means

$$\begin{pmatrix} -2 - 1 & 3 \\ -3 & 4 - 1 \end{pmatrix} \begin{pmatrix} r \\ s \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

There are infinitely many possible solutions but we simply take $r = 0$ and $s = 1/3$, so

$$\vec{p} = \begin{pmatrix} 0 \\ 1/3 \end{pmatrix}.$$

The solution is

$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = c_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} \exp(t) + c_2 \left(\begin{pmatrix} 1 \\ 1 \end{pmatrix} t + \begin{pmatrix} 0 \\ 1/3 \end{pmatrix} \right) \exp(t),$$

or $x(t) = c_1 \exp(t) + c_2 t \exp(t)$ and $y(t) = c_1 \exp(t) + \frac{1}{3} c_2 \exp(t) + c_2 t \exp(t)$.